

COMLINEAR® CLC1008, CLC2008

0.5mA, Low Cost, 2.5 to 5.5V, 75MHz Rail-to-Rail Amplifiers

FEATURES

- 505µA supply current
- 75MHz bandwidth
- Input voltage range with 5V supply: -0.3V to 3.8V
- Output voltage range with 5V supply: 0.07V to 4.86V
- 50V/µs slew rate
- 12nV/√Hz input voltage noise
- 15mA linear output current
- Fully specified at 2.7V and 5V supplies
- Replaces AD8031 in $V_S \le 5$ applications

APPLICATIONS

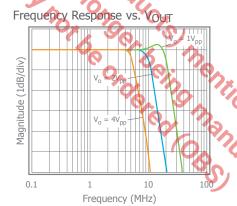
- Portable/battery-powered applications
- Mobile communications, cell phones, pagers
- ADC buffer
- Active filters
- Portable test instruments
- Signal conditioning
- Medical Equipment
- Portable medical instrumentation

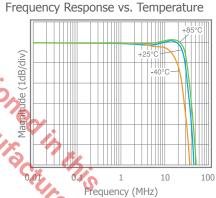
General Description

The COMLINEAR CLC1008 (single) and CLC2008 (dual) offer superior dynamic performance with 75MHz small signal bandwidth and 50V/ μ s slew rate. These amplifiers use only 505 μ A of supply current and are designed to operate from a supply range of 2.5V to 5.5V (± 1.25 to ± 2.75). The combination of low power, high output current drive, and rail-to-rail performance make the CLC1008 and CLC2008 well suited for battery-powered communication/computing systems.

The combination of low cost and high performance make the CLC1008 and CLC2008 suitable for high volume applications in both consumer and industrial applications such as wireless phones, scanners, and color copiers.

Typical Performance Examples



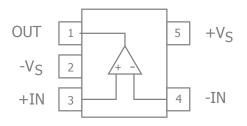


Ordering Information

Part Number	Package	Pb-Free	RoHS Compliant	Operating Temperature Range	Packaging Method
CLC1008IST5X	SOT23-5	Yes	Yes	-40°C to +85°C	Reel
CLC2008ISO8X	SOIC-8	Yes	Yes	-40°C to +85°C	Reel

Moisture sensitivity level for all parts is MSL-1.

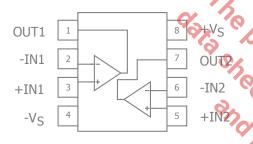
CLC1008 Pin Configuration



CLC1008 Pin Assignments

Pin No.	Pin Name	Description
1	OUT	Output
2	-V _S	Negative supply
3	+IN	Positive input
4	-IN	Negative input
5	+V _S	Positive supply

CLC2008 Pin Configuration



CLC2008 Pin Configuration

<i>></i>	Pin No.	Pin Name	Description
7. 70	1	OUT1	Output, channel 1
JOHVS	2	-IN1	Negative input, channel 1
Ούτο	3	+IN1	Positive input, channel 1
_	4	-V _S	Negative supply
-IN2	5/	+IN2	Positive input, channel 2
+IN2	6 0	-IN2	Negative input, channel 2
	7	OUT2	Output, channel 2
	8 0	O+V _S	Positive supply
	6	ordered (Negative input, channel 2 Output, channel 2 Positive supply

Absolute Maximum Ratings

The safety of the device is not guaranteed when it is operated above the "Absolute Maximum Ratings". The device should not be operated at these "absolute" limits. Adhere to the "Recommended Operating Conditions" for proper device function. The information contained in the Electrical Characteristics tables and Typical Performance plots reflect the operating conditions noted on the tables and plots.

Parameter	Min	Max	Unit
Supply Voltage	0	6	V
Input Voltage Range	-V _s -0.5V	+V _S +0.5V	V
Continuous Output Current	-30	30	mA

Reliability Information

Parameter	Min	Тур	Max	Unit
Junction Temperature			175	°C
Storage Temperature Range	-65		150	°C
Lead Temperature (Soldering, 10s)			260	°C
Package Thermal Resistance				
5-Lead SOT23		221		°C/W
8-Lead SOIC		100		°C/W

Notes:

Package thermal resistance (θ_{JA}), JDEC standard, multi-layer test boards, still air.

Recommended Operating Conditions

Parameter	MinC ₂ Typ	Max	Unit
Operating Temperature Range	C40	+85	°C
Supply Voltage Range	2.5	5.5	V
	ordered man	oned in this	
		(A)	

Electrical Characteristics at +2.7V

 $T_A=25^{o}C,\,V_S=+2.7V,\,R_f=R_g=1k\Omega,\,R_L=1k\Omega$ to $V_S/2,\,G=2;$ unless otherwise noted.

Symbol	Parameter	Conditions	Min	Тур	Max	Units
Frequency D	Domain Response					
UGBW _{SS}	Unity Gain -3dB Bandwidth	$G = +1$, $V_{OUT} = 0.05V_{pp}$, $R_f = 0$		65		MHz
BW _{SS}	-3dB Bandwidth	$G = +2, V_{OUT} < 0.2V_{pp}$		30		MHz
BW _{LS}	Large Signal Bandwidth	$G = +2$, $V_{OUT} = 2V_{pp}$		12		MHz
GBWP	Gain Bandwidth Product	$G = +11, V_{OUT} = 0.2V_{pp}$		28		MHz
Time Domai	n Response		,			
t _R , t _F	Rise and Fall Time	V _{OUT} = 0.2V step; (10% to 90%)		7.5		ns
t _S	Settling Time to 0.1%	V _{OUT} = 1V step		60		ns
OS	Overshoot	V _{OUT} = 1V step		10		%
SR	Slew Rate	2V step, G = -1		40		V/µs
Distortion/N	oise Response		<u>'</u>	'		'
HD2	2nd Harmonic Distortion	$V_{OUT} = 1V_{pp}$, 1MHz		-67		dBc
HD3	3rd Harmonic Distortion	$V_{OUT} = 1V_{pp}$, 1MHz		-72		dBc
THD	Total Harmonic Distortion	$V_{OUT} = 1V_{pp}$, 1MHz		65		dB
e _n	Input Voltage Noise	10kHz		12		nV/√Hz
DC Performa	ance		<u>'</u>			
V _{IO}	Input Offset Voltage	O _A		0		mV
dV _{IO}	Average Drift	P _A D _A		10		μV/°C
I _b	Input Bias Current	5 0 0		1.2		μΑ
dI _b	Average Drift	DO DO DO SOLO		3.5		nA/°C
I _{OS}	Input Offset Current	Po Po Cx		30		nA
PSRR	Power Supply Rejection Ratio (1)	DQ Z SQ SY	60	66		dB
A _{OL}	Open-Loop Gain	V _{OUT} = V _S / 2		98		dB
I _S	Supply Current	per channel		470		μΑ
Input Chara	cteristics	0/2 10 11/2				
R _{IN}	Input Resistance	Non-inverting Non-inverting	2	9		ΜΩ
C _{IN}	Input Capacitance	0/ 10.	0	1.5		pF
CMIR	Common Mode Input Range	DC $V_{OUT} = V_S / 2$ per channel Non-inverting DC, $V_{CM} = 0V$ to $V_S - 1.5$	k b.	-0.3 to 1.5		V
CMRR	Common Mode Rejection Ratio	DC, $V_{CM} = 0V \text{ to } V_S - 1.5$	80. 9	74		dB
Output Char	acteristics	9	C.	S		
V	Outout Valtage Suine	$R_L = 1k\Omega$ to $V_S/2$	C	0.09 to 2.53		V
V _{OUT}	Output Voltage Swing	$R_L = 10k\Omega$ to $V_S/2$		0.05 to 2.6		V
I _{OUT}	Output Current			±15		mA
I_{SC}	Short Circuit Output Current			±30		mA

Notes:

1. 100% tested at 25°C

Electrical Characteristics at +5V

 $T_A=25^{\circ}C,\,V_S=+5V,\,R_f=R_g=1k\Omega,\,R_L=1k\Omega$ to $V_S/2,\,G=2;$ unless otherwise noted.

Symbol	Parameter	Conditions	Min	Тур	Max	Units
Frequency D	Domain Response	'				
UGBW _{SS}	Unity Gain -3dB Bandwidth	$G = +1$, $V_{OUT} = 0.05V_{pp}$, $R_f = 0$		75		MHz
BW _{SS}	-3dB Bandwidth	$G = +2, V_{OUT} < 0.2V_{pp}$		35		MHz
BW _{LS}	Large Signal Bandwidth	$G = +2$, $V_{OUT} = 2V_{pp}$		15		MHz
GBWP	Gain Bandwidth Product	$G = +11, V_{OUT} = 0.2V_{pp}$		33		MHz
Time Domai	n Response					
t _R , t _F	Rise and Fall Time	V _{OUT} = 0.2V step; (10% to 90%)		6		ns
t _S	Settling Time to 0.1%	V _{OUT} = 1V step		60		ns
OS	Overshoot	V _{OUT} = 1V step		12		%
SR	Slew Rate	2V step, G = -1		50		V/µs
Distortion/N	oise Response					
HD2	2nd Harmonic Distortion	$V_{OUT} = 2V_{pp}$, 1MHz		-64		dBc
HD3	3rd Harmonic Distortion	$V_{OUT} = 2V_{pp}$, 1MHz		-62		dBc
THD	Total Harmonic Distortion	$V_{OUT} = 2V_{pp}$, 1MHz		60		dB
e _n	Input Voltage Noise	> 10kHz		12		nV/√Hz
DC Performa	ance					
V _{IO}	Input Offset Voltage (1)	Q _A O _A	-5	-1	5	mV
dV _{IO}	Average Drift	P _A D _A		10		μV/°C
I_{b}	Input Bias Current (1)	3 0 0	-3.5	1.2	3.5	μΑ
dI _b	Average Drift	4. 6 %		3.5		nA/°C
I _{OS}	Input Offset Current (1)	Po Po Cx		30	350	nA
PSRR	Power Supply Rejection Ratio (1)	DQ Z SO S	60	66		dB
A _{OL}	Open-Loop Gain (1)	V _{OUT} = V _S / 2	65	80		dB
I_{S}	Supply Current (1)	per channel		505	620	μΑ
Input Chara	cteristics	10 10 18	•			
R _{IN}	Input Resistance	Non-inverting	95	9		ΜΩ
C _{IN}	Input Capacitance	0/ 10.	0	1.5		pF
CMIR	Common Mode Input Range	DC V _{OUT} = V _S / 2 per channel Non-inverting DC, V _{CM} = 0V to V _S - 1.5	45 h	-0.3 to 3.8		V
CMRR	Common Mode Rejection Ratio (1)	DC, $V_{CM} = 0V \text{ to } V_S - 1.5$	65	74		dB
Output Char	racteristics	-	C.	S		
V	Outrout Valtage Cuing	$R_L = 1k\Omega$ to $V_S/2$ (1)	0.2 to 4.65	0.13 to 4.73		V
V _{OUT}	Output Voltage Swing	$R_L = 10k\Omega$ to $V_S/2$		0.08 to 4.84		V
I _{OUT}	Output Current			±15		mA
I_{SC}	Short Circuit Output Current			±30		mA

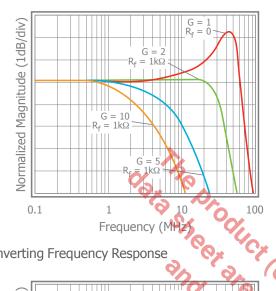
Notes:

1. 100% tested at 25°C

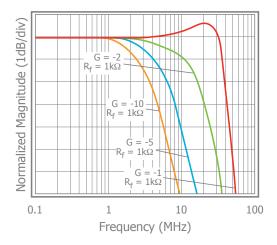
Typical Performance Characteristics

 $T_A = 25$ °C, $V_S = +5V$, $R_f = R_q = 1k\Omega$, $R_L = 1k\Omega$ to $V_S/2$, G = 2; unless otherwise noted.

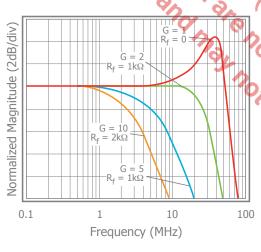
Non-Inverting Frequency Response at $V_S = 5V$



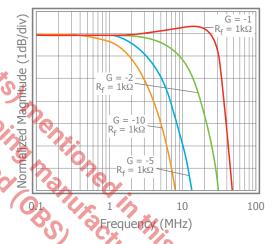
Inverting Frequency Response at $V_S = 5V$



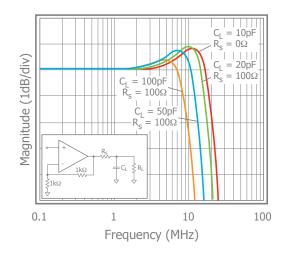




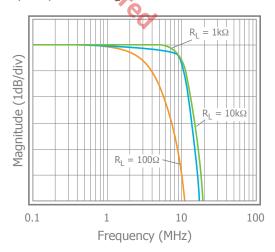
Inverting Frequency Response



Frequency Response vs. C_L



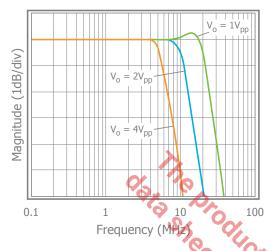
Frequency Response vs. R



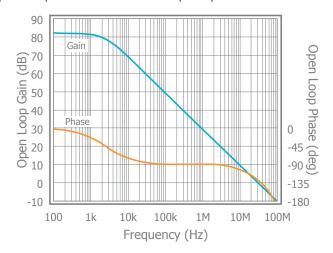
Typical Performance Characteristics

 $T_A = 25$ °C, $V_S = +5V$, $R_f = R_q = 1k\Omega$, $R_L = 1k\Omega$ to $V_S/2$, G = 2; unless otherwise noted.

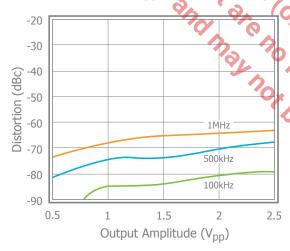
Frequency Response vs. V_{OUT}



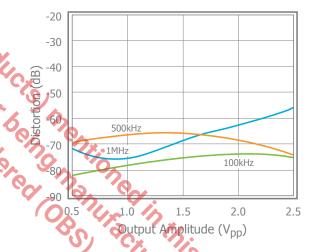
Open Loop Gain & Phase vs. Frequency



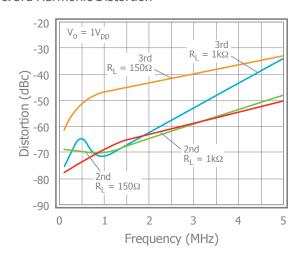
2nd Harmonic Distortion vs. V_{OUT}



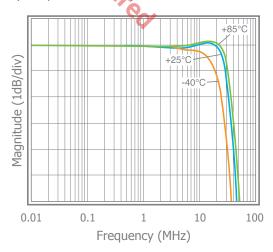
3rd Harmonic Distortion vs. V_{OUT}



2nd & 3rd Harmonic Distortion

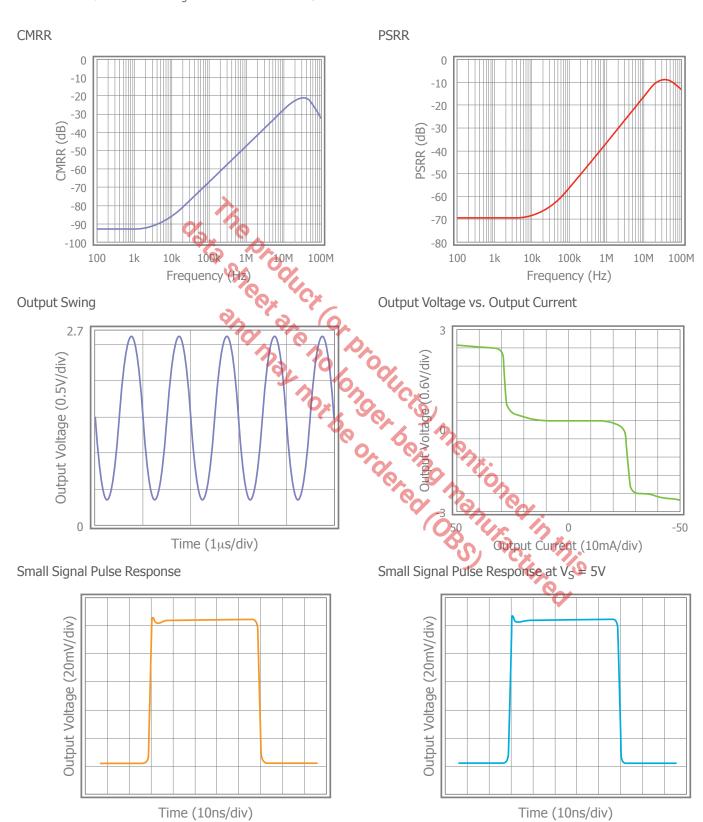


Frequency Response vs. Temperature



Typical Performance Characteristics - Continued

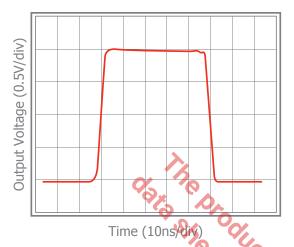
 $T_A=25$ °C, $V_S=+5V$, $R_f=R_g=1k\Omega$, $R_L=1k\Omega$ to $V_S/2$, G=2; unless otherwise noted.



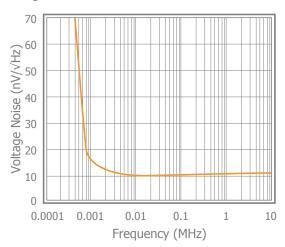
Typical Performance Characteristics - Continued

 $T_A = 25$ °C, $V_S = +5V$, $R_f = R_q = 1k\Omega$, $R_L = 1k\Omega$ to $V_S/2$, G = 2; unless otherwise noted.

Large Signal Pulse Response at $V_S = 5V$



Input Voltage Noise



Time (10ns/8) Olycon Proposition of Decision Proposition Propositi

Application Information

General Description

The CLC1008 family are a single supply, general purpose, voltage-feedback amplifiers fabricated on a complementary bipolar process. The CLC1008 offers 75MHz unity gain bandwidth, 50V/µs slew rate, and only 505µA supply current. It features a rail-to-rail output stage and is unity gain stable.

Figures 1, 2, and 3 illustrate typical circuit configurations for non-inverting, inverting, and unity gain topologies for dual supply applications. They show the recommended bypass capacitor values and overall closed loop gain equations. Figure 4 shows the typical non-inverting gain circuit for single supply applicaitons.

The common mode input range extends to 300mV below ground in single supply operation. Exceeding these values will not cause phase reversal. However, if the input voltage exceeds the rails by more than 0.5V, the input ESD devices will begin to conduct.

The design uses a Darlington output stage. The output stage is short circuit protected and offers "soft" saturation protection that improves recovery time.

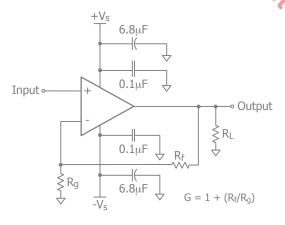


Figure 1. Typical Non-Inverting Gain Circuit

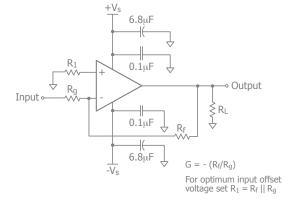


Figure 2. Typical Inverting Gain Circuit

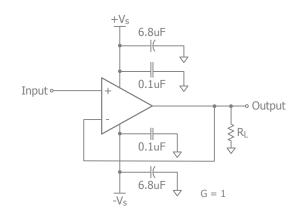
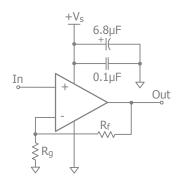


Figure 3. Unity Gain Circuit



Pigure 4. Single Supply Non-Inverting Gain Circuit

Pesnonse at a gain of +2, a feedback resi

Lillustrates the CLC1 For optimum response at a gain of +2, a feedback resistor of $1k\Omega$ is recommended. Figure 5 illustrates the CLC1008 frequency response with both $1k\Omega$ and $2k\Omega$ feedback resistors.

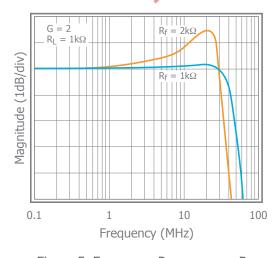


Figure 5. Frequency Response vs. Rf

Power Dissipation

Power dissipation should not be a factor when operating under the stated 1k ohm load condition. However, applications with low impedance, DC coupled loads should be analyzed to ensure that maximum allowed junction temperature is not exceeded. Guidelines listed below can be used to verify that the particular application will not cause the device to operate beyond it's intended operating range.

Maximum power levels are set by the absolute maximum junction rating of 150°C. To calculate the junction temperature, the package thermal resistance value Theta_{1A} (Θ_{1A}) is used along with the total die power dissipation.

$$T_{Junction} = T_{Ambient} + (\Theta_{JA} \times P_{D})$$

Where T_{Ambient} is the temperature of the working environment.

In order to determine PD, the power dissipated in the load needs to be subtracted from the total power delivered by the supplies.

$$P_D = P_{supply} - P_{load}$$

Supply power is calculated by the standard equation.

$$\begin{aligned} P_{supply} &= V_{supply} \times I_{RMS \ supply} \\ V_{supply} &= V_{S^+} - V_{S^-} \end{aligned}$$

Power delivered to a purely resistive load is:

$$P_{load} = ((V_{LOAD})_{RMS^2})/Rload_{eff}$$

The effective load resistor (Rloadeff) will need to include the effect of the feedback network. For instance,

Rloadeff in Figure 3 would be calculated as:

$$R_L \parallel (R_f + R_a)$$

These measurements are basic and are relatively easy to perform with standard lab equipment. For design purposes however, prior knowledge of actual signal levels and load impedance is needed to determine the dissipated power. Here, PD can be found from

$$P_D = P_{Quiescent} + P_{Dynamic} - P_{Load}$$

Quiescent power can be derived from the specified I_S values along with known supply voltage, V_{Supply}. Load power can be calculated as above with the desired signal amplitudes using:

$$(V_{LOAD})_{RMS} = V_{PEAK} / \sqrt{2}$$

$$(I_{LOAD})_{RMS} = (V_{LOAD})_{RMS} / Rload_{eff}$$

The dynamic power is focused primarily within the output stage driving the load. This value can be calculated as:

$$P_{DYNAMIC} = (V_{S+} - V_{LOAD})_{RMS} \times (I_{LOAD})_{RMS}$$

Assuming the load is referenced in the middle of the power rails or $V_{\text{supply}}/2$.

The CLC1008 is short circuit protected. However, this may not guarantee that the maximum junction temperature (+150°C) is not exceeded under all conditions. Figure 6 shows the maximum safe power dissipation in the package vs. the ambient temperature for the packages available.

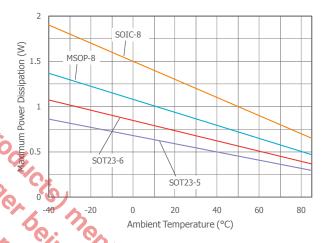


Figure 6 Maximum Power Derating

Driving Capacitive Loads

Increased phase delay at the output due to capacitive loading can cause ringing peaking in the frequency response, and possible unstable behavior. Use a series resistance, Rs, between the amplifier and the load to help improve stability and settling performance. Refer to Figure 7.

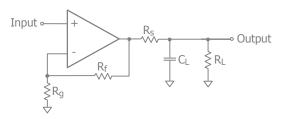


Figure 7. Addition of R_S for Driving Capacitive Loads

Table 1 provides the recommended R_S for various capacitive loads. The recommended R_S values result in approximately <1dB peaking in the frequency response. The Frequency Response vs. C_L plot, on page 4, illustrates the response of the CLCx008.

C _L (pF)	R _S (Ω)	-3dB BW (kHz)
10pF	0	22
20pF	100	19
50pF	100	12
100pF	100	10.2

Table 1: Recommended R_S vs. C_L

For a given load capacitance, adjust R_S to optimize the tradeoff between settling time and bandwidth. In general, reducing R_S will increase bandwidth at the expense of additional overshoot and ringing.

Overdrive Recovery

An overdrive condition is defined as the point when either one of the inputs or the output exceed their specified voltage range. Overdrive recovery is the time needed for the amplifier to return to its normal or linear operating point. The recovery time varies, based on whether the input or output is overdriven and by how much the range is exceeded. The CLC1008 and CLC2008 will typically recover in less than 20ns from an overdrive condition. Figure 8 shows the CLC1008 in an overdriven condition.

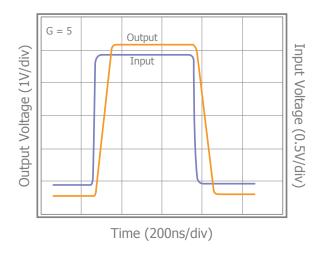


Figure 8. Overdrive Recovery

Layout Considerations

General layout and supply bypassing play major roles in

high frequency performance. CADEKA has evaluation boards to use as a guide for high frequency layout and as an aid in device testing and characterization. Follow the steps below as a basis for high frequency layout:

- Include 6.8μF and 0.1μF ceramic capacitors for power supply decoupling
- Place the 6.8µF capacitor within 0.75 inches of the power pin
- Place the 0.1µF capacitor within 0.1 inches of the power pin
- Remove the ground plane under and around the part, especially near the input and output pins to reduce parasitic capacitance
- Minimize all trace lengths to reduce series inductances

Refer to the evaluation board layouts below for more information.

Evaluation Board Information

The following evaluation boards are available to aid in the testing and layout of these devices:

Evaluation Board	Products
CEB002	CLC1008 in SOT23
CEB003	CLC1008 in SOIC
CEB006	CLC2008 in SOIC
CEB010	CLC2008 in MSOP

Evaluation Board Schematics

Evaluation board schematics and layouts are shown in Figures 8-14. These evaluation boards are built for dual-supply operation. Follow these steps to use the board in a single-supply application:

- 1. Short -Vs to ground.
- 2. Use C3 and C4, if the -V_S pin of the amplifier is not directly connected to the ground plane.

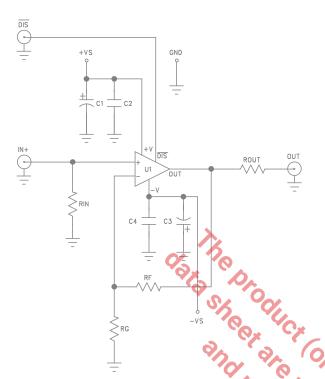


Figure 8. CEB002 & CEB003 Schematic

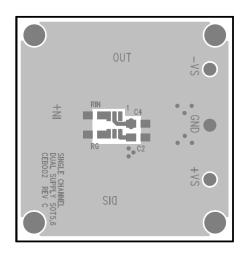


Figure 9. CEB002 Top View

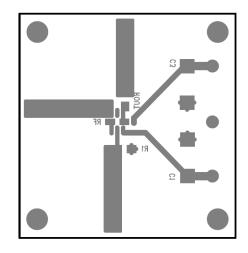


Figure 10. CEB002 Bottom View

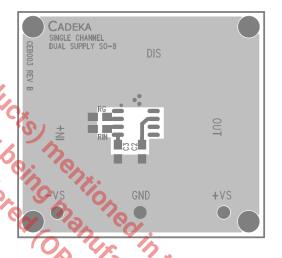


Figure 11. CEB003 Top View

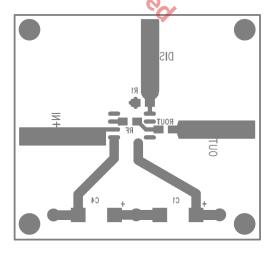


Figure 12. CEB003 Bottom View

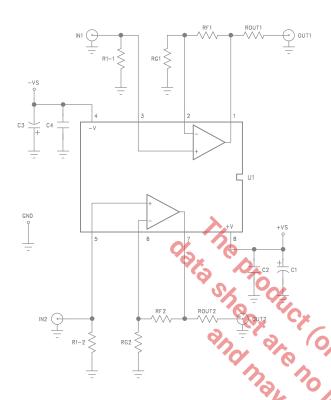


Figure 11. CEB006 & CEB010 Schematic

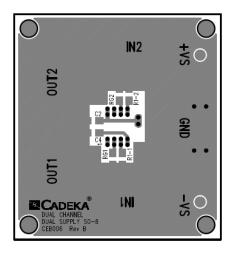


Figure 12. CEB006 Top View

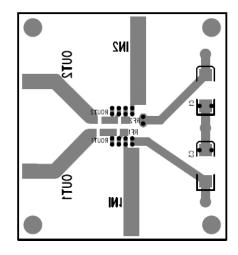


Figure 13. CEB006 Bottom View

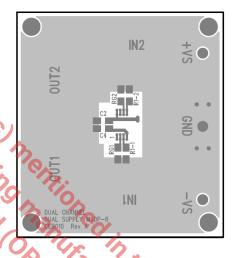


Figure 15. CEB010 Top View

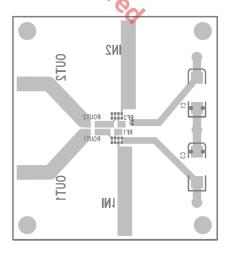
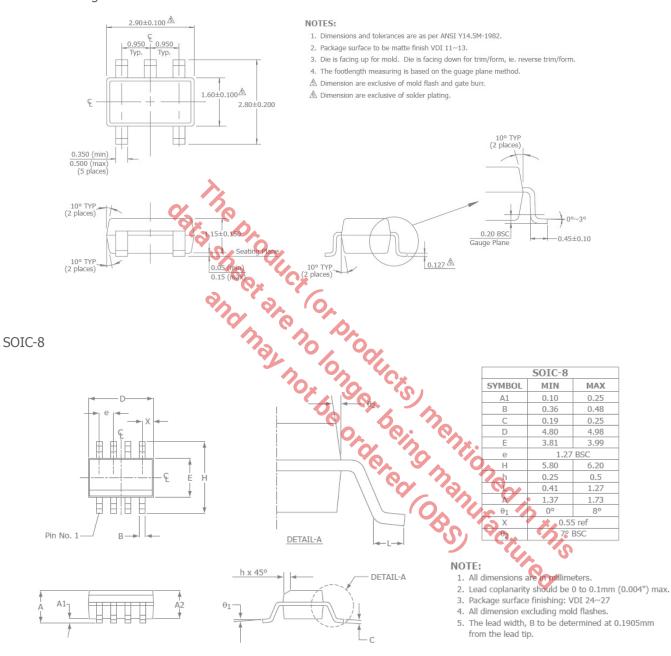


Figure 16. CEB010 Bottom View

Mechanical Dimensions

SOT23-5 Package



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For Further Assistance:

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